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In the case of an aerial stereo pair, radial distortion is quite small, less than 1 mm. In the case of a ground glass stereo pair, radial distortion is up to around 0.5 mm when the camera is on a tripod, and larger distortions will be present when the camera is hand-held. A large radial distortion can cause the scene in the vicinity of the camera to appear as an ellipse rather than a circle. Although a large degree of radial distortion is to be expected when the camera is hand-held, this must be corrected for in order to ensure proper fusion of the two images with a large or radial disparity. The pincushion distortion is very similar to barrel distortion, except that the distortion is produced in the vertical rather than the horizontal direction. The vertical length of the image is increased or decreased in order to form an ellipse or inverted V-shape, respectively. The pincushion distortion is produced due to optical imperfections such as lens flare, irregular illumination, specular reflections, particularly near the edges of the frame and near bright specular spots on the ground or wall. When considering recording a stereoscopic pair, the first consideration is whether each image plane is a plane of constant positive height (MPH), or a plane of constant negative height (MNH). The second consideration is the relationship between the centre of each image to the plane of constant positive height. Released: 10 January 2006. Esri ArcGIS 8.5 is the first version of the 8.5-series released since the 8.0-series in 1999. It incorporates several new features, including support for coordinate system attributes, multiple function keys, and improved data browsing. Version 8.5 also addresses many bugs in the earlier 8.x versions. An updated Reference Manual is available to help users transition from ArcGIS 8.x to 8.5. New data sources, including open source imagery and environmental information.

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This approach is best for viewing the images using a stereoscopic viewer and not for saving them in a file format for archiving. You should avoid saving the raw images in an H.264 or H.265 file format because they can have large file sizes and are not compressed properly. Other methods include flying in 3-D using anaglyph glasses and the Virtual Reality Modeling Language (VRML), where the output is head-mounted displays (HMDs) that provide the stereoscopic viewing as well as 3D rendering. These include DDD's TriDef Visualizer for Google Earth and Tripod's VRViewer for Google Earth, which are demonstrated in Figure 2-3. These software viewers work with a range of 3-D glasses, which in turn require the use of a computer with a display screen capable of producing a stereoscopic image (and preferably high-definition and/or high-density displays). DDD's 3-D Experience package also includes the TriDef Visualizer for Google Earth Viewer (for Windows only) and the Tripod Viewer for Google Earth, which support a range of stereo formats and also offer HMD compatibility. In addition to these viewers, Microsoft has also released an open source Java viewer for the Google Earth KML plugin, GoogleVRViewer [3]. The USGS BRD UMESC team's work is at an early stage and it does not yet have a computer model of the study area, so there is little information about how the stereo processing will be done. The choice of autostereoscopic projection and the use of a projector to enlarge the projection seems optimal to the team as it would provide the best possible quality images, especially when displayed on a variety of computer screens, with no loss in image sharpness or distortions from the projector's own characteristics. It also seems that a monoscopic display would be possible with the current stereoscopic anaglyph process, and there would also be a trade-off of quality loss. However, the project team is looking for further developments in this area to increase the quality of the stereo display. Obtaining dedicated stereoscopic displays may eventually be necessary to improve image quality, resolution, and the quality of the stereo display itself. 5ec8ef588b

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